## <<导弹制导原理>>

#### 图书基本信息

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#### 内容概要

The intent of this book is to present guidance and control principle of tactical missiles. It includes basicconcepts of guided missile, fundamental concepts of vehicle dynamics, dynamical equatio and kinematicequatio of vehicle, longitudinal state equation and trafer functio, lateral state equation and traferfunctio, fundamental principle of missile guidance and control system, guidance laws, autopilot design,command guidance systems, homing guidance systems, and guidance and control system hardware-in-the-loopsimulation. This book is suitable for international postgraduate and advanced undergraduates majoring in navigation,guidance and control, and also suitable for engineering and technical peonnel engaged in the design anddevelopment of guided missiles.

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#### 书籍目录

CHAPTER 1	Introduction to Missile Guidance
<b>CHAPTER 2</b>	Basic Knowledge of Flight Dynamics

CHAPTER 3 Equatio of Motion for Vehicle

CHAPTER 4 Longitudinal Motion

**CHAPTER 5 Lateral Motion** 

CHAPTER 6 Flight Control of Missile

CHAPTER 7 Guidance Laws

CHAPTER 8 Autopilot Design

CHAPTER 9 Command Guidance Systems

CHAPTER 10 Homing Guidance Systems

CHAPTER 11 Hardware-in-the-loop Simulation of Guidance and Control

System

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#### 章节摘录

版权页:插图: When a vehicle flies in the air,it undergoes resistance which the air exerts. In order to overcome the resistance, it is necessary to consume engine power. Not only the vehicle wings produce resistance, but also any other part exposing to the air yields resistance. So the wing resistance can not represent the total resistance. As for a low speed vehicle, there are the friction resistance, the pressure deference resistance, and the induced resistance. For a supersonic vehicle, the shock wave results in the wave resistance. Anyway, the coefficient of drag consists of two terms as follows: Co=CoO+Coi (2.4-13) where CD0=zero lift drag coefficient, CDi=lift induced drag coefficient. In the case of a small angle of attack, the drag coefficient is represented as CD=-CDo(Ma)+K(Ma)C2L (2.4-14) Moreover, the drag coefficient depends on Mach number. Figure 2.4-5 shows the CDo versus Mach number Ma curve in the case of =0. Figure 2.4-6 shows the CL versus CD curve, called lift-drag polar curve. It indicates that a vehicle gets lift at the cost of producing resistance.

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