### <<铁路及磁悬浮系统提速和服务技术>>

#### 图书基本信息

书名:<<铁路及磁悬浮系统提速和服务技术会议论文集>>

13位ISBN编号: 9787811043617

10位ISBN编号: 7811043610

出版时间:2006-07-01

出版时间:西南交通大学出版社

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页数:366

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#### 内容概要

The Objectectives off STECH'06 , the Fourth International Symposium oit Speed—up and ServiceTechnology for Railway andMaglev Systems , which held on July 13—16 of2006inChangdu , China , are to present and discussthe state 0f the ard Of the scientific and technical aspects of high speed and heavy haul railways , maglev and urban transportation systams Recent years the railways in China have been developed rapidly The total railway line length has exceeded 70 , 000km Several times for the raising speeds oftrains have been carried out and the speed 0n the main lines has reached 140 to 160 km / h This year the train speed will further reach to 200km / h , and several high speed fines with speed from 200 to 350km / h are under construction The maglev trains are successfully operating in Shanghai.

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#### 书籍目录

Invited PaperHigh-speed Train Dynamic Environment and Its Impact Assessment Assessment Zhiyun ShenSiytgwest Jiaotong University, ChinaAdvanced Control and Monitoring for Railway Vehicle SuspensionsRoger Goodall, TXMeiLoughborough University, UKCollaborative Research for Railway Vehicle Systems Possibility of Innovative and Attractive SystemYoshihiro SudaThe University of Tokyo, Tokyo, Japan VehicleOn the Application of Autonomy to Railway Vehicle's Assembly Groups Johannes Gregor, Arne Berger, Torsten DellmannDynamic Problems in Developing Bogies for Wagons with Increased Capacity Yu, Boronenko, A. Orlova, E. Rudakova Sliding Mode Control of Wheel Slip Prevention with Robust Variable Structure System Observer for Railway Vehicles Hiro-o Yamazaki, Takanori Obara, Takayoshi Kamada, Masao Nagai Dynamic Simulation of Railway Train Braking Ren Luo, Jing Zeng Study on Coupled Characteristic of Coupled Wheelset Maoru Chi, Weihua Zhang, Jing Zeng, Huanyun Dai, Pingbo WuActive Vibration Control of Elastic Vehicle Body with Smart Structure Takayuki Tohtake, Masao Nagai, Takayoshi Kamada and Hidehisa Yoshida hellip; hellip; Infrastructure Boundary Problem Environment and Energy Safety Technology and Accident Analysis Urban Transportation Maglev and Linear Motor Drive Technology Operation Managment and Maintenance Intelligent Transportation System Other Topics

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#### 章节摘录

For easy experiments for lateral dynamics, the traction device with actuator outside of the vehicle is adopted. The traction system, which consists of a gantry robot actuated with AC motor and a linear guide lies parallel to the straight track, works to keep the vehicle with desired velocity along the straight section. The patterns of vehicle velocity on this straight track are suitably controlloed by the servo control up to 3.0 m/s. The vehicle is released from the traction system after gaining the desired velocity at the end of the straigh track, and then runs into curved track by means of its applied initial velocity. transition curve is sinusoidal transition curve and the radius of constant curve is 3.3m. The rail cant is freely changed by the adjustable cant mechanism. In the curved section, gradient (13%) is given so that the model vehicle should not stop on the cured track owing to the resistant force generated by flange contact force of wheel. As for thye ground measurement system, the system with strain gauge and strain meter is adopted to measure the vertical and lateral forces of rails. Using the measuring system, applied loads by each wheel can be measured when the wheel pass the point. The measuring system is able to set at any point on the track only changing the position of strain gauges. … …

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